

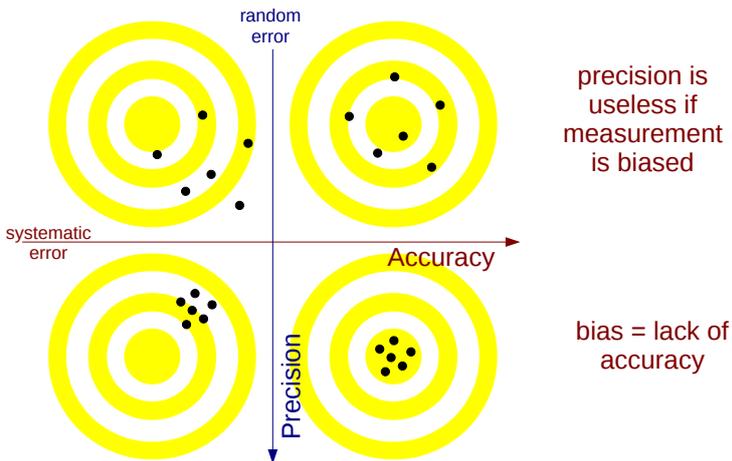
Topics

Sub-Pixel Precision Measurement in the Point-Sampling Model

- What is important for a measure?
 - accuracy (bias), precision, sampling-invariance
- How does filtering affect the measurement?
- The point-sampling model:
 - image formation, band limit, sampling, Fourier analysis
- Soft clipping
- Measurement:
 - area
 - perimeter
 - curvature
 - bending energy
 - Euler number (object count)

Accuracy vs. precision

Sampling invariance



- The choice of sampling grid should not influence the measurement result:
 - translation invariance
 - rotation invariance
 - scaling invariance
 - when counting pixels, a denser grid gives higher precision
- Methods we talk about today are invariant to scaling!
 - given a properly sampled band-limited function
 - thus: there is a minimum sampling density
 - band limit gives maximum attainable precision

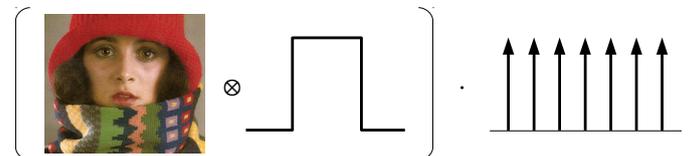
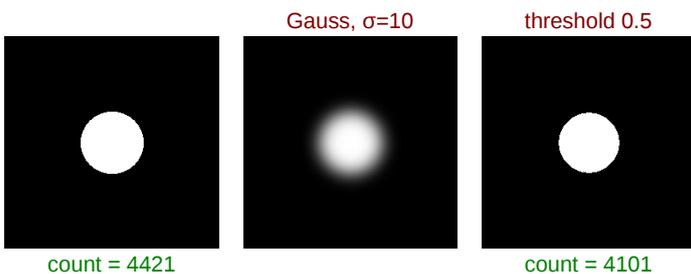


Effects of filtering

The point-sampling model

- Low-pass filtering always moves the edges inwards
 - (Inwards = in the direction of curvature)
 - This is also true for median filtering, for example!
- Edge-preserving smoothing filters sometimes also move edges

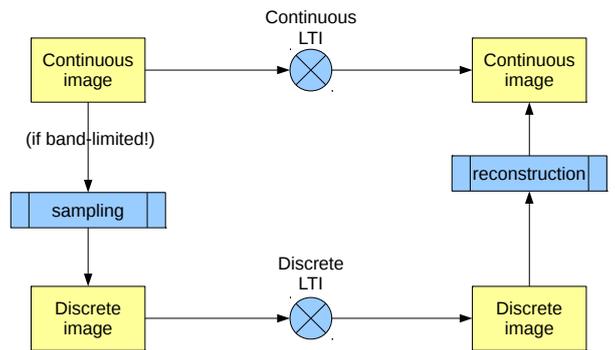
- Point sampling is what is assumed in signal theory
- Point sampling is only useful if the image is band limited
 - otherwise we get aliasing
 - $\text{sampling frequency} > 2 \cdot \text{band limit}$ (Nyquist)
- CCDs do not point-sample
 - but: can be modelled by a uniform filter followed by point sampling



Band-limited images

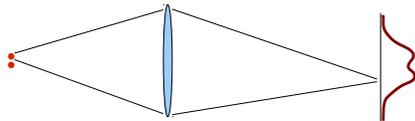
- Any optical image formation system imposes a band limit
- A sampled band-limited image *exactly* represents the continuous band-limited image
 - if sampled properly, of course
- The continuous band-limited image is a version of real world that lacks very high frequencies
 - i.e. small details
- This smooth image preserves large-scale geometric properties of the imaged objects, but not small scale ones
 - as in “the infinite coastline of Britain”

The sampling property

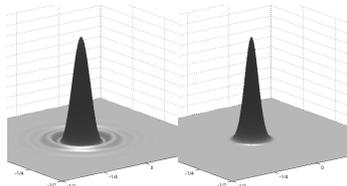


Optical image formation

- Image formation system (e.g. lenses) creates a band-limited image — imposes resolution

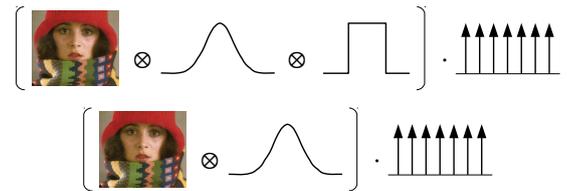


- Standard optics' point-spread function (PSF) can be approximated by a Gaussian
 - ideal lens has Airy function for PSF
 - but lens imperfections are unavoidable



Optical image formation

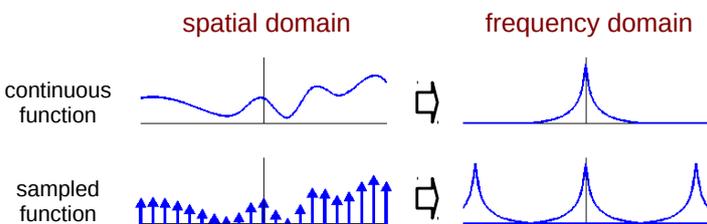
- The image is smoothed by a PSF (convolution!) before sampling



- Neither the smoothing nor the sampling change the total amount of light in the image

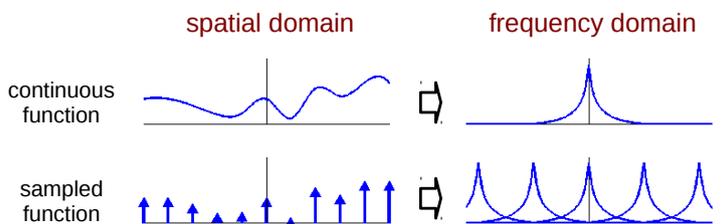


What happens in the Fourier domain



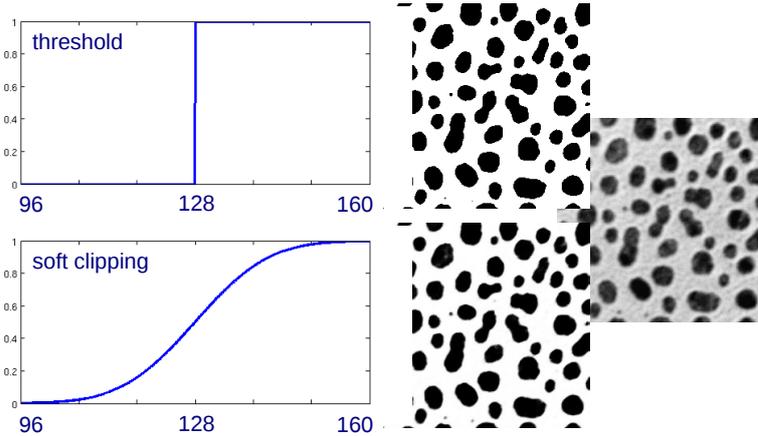
- The 0th frequency is proportional to the total amount of light
- 0th frequency is unaltered by sampling
- Sum of samples is equal (proportional) to integral over continuous function

What happens in the Fourier domain

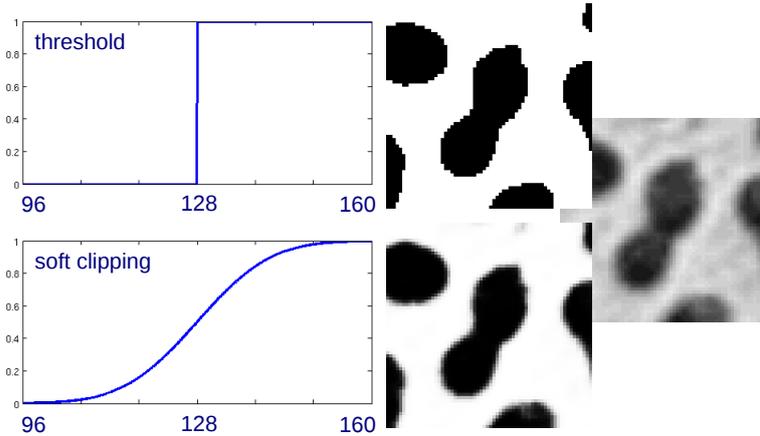


- But: aliasing can affect the 0th frequency!
- Sum of samples is equal (proportional) to integral over continuous, band-limited function if sampled correctly

Threshold vs. soft clipping

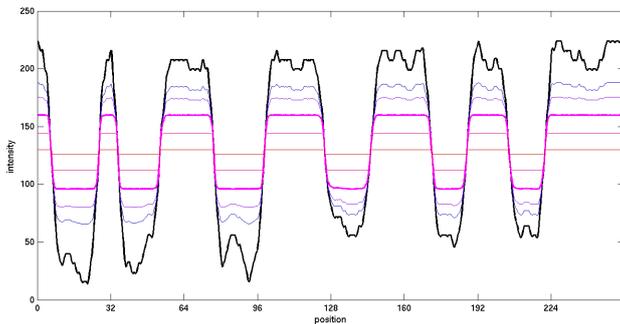


Threshold vs. soft clipping



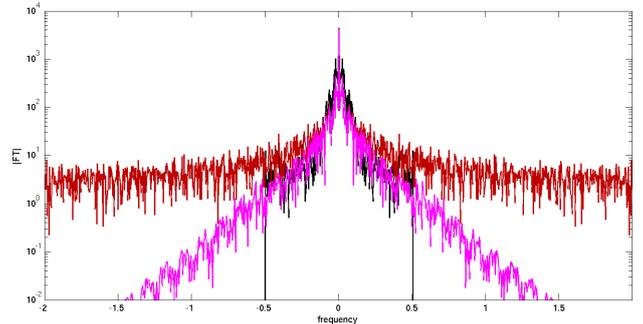
Soft clipping

- Selecting a proper range is important
 - too small: introduction of aliasing
 - too large: background and foreground not uniform



Soft clipping

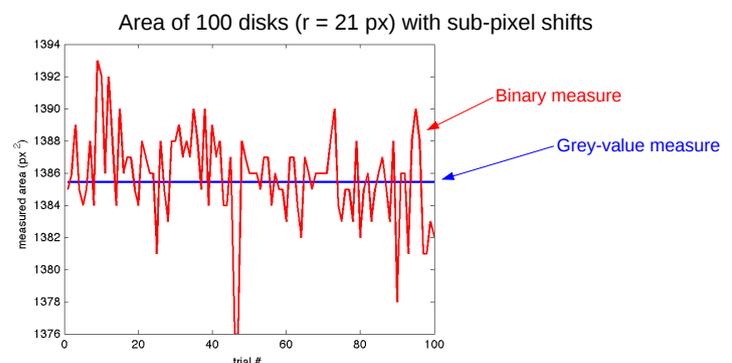
- Interpolated 4x by padding the Fourier transform before soft clipping
 - input, soft clipping, threshold



Possible measures

- Area (2D) / volume (3D)
 - integral over image (sum of grey values)
 - effectively dimensionality-independent
- Perimeter (2D) / surface area (3D)
 - we convert the problem to a volume problem
 - effectively dimensionality-independent
- (Isophote) curvature (2D/3D)
 - based on 2nd derivative along the contour
- Bending energy (2D/3D)
 - integrating squared curvature along contour
- Euler number (object count, 2D)
 - integral of curvature along contour is constant

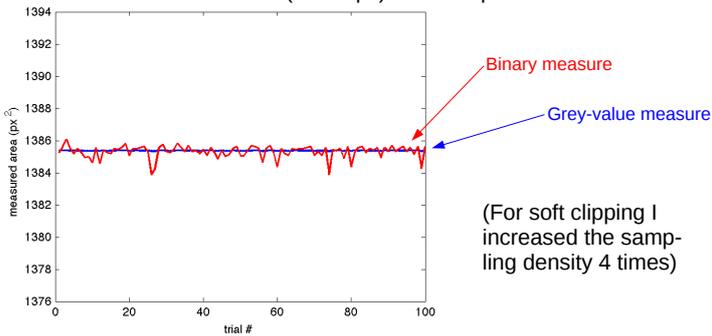
2D area (ideal case)



Expected measure: 1385.442360 px²
 Grey-value measure: 1385.442352 ± 0.000001 px² (std = 0.000006)
 Binary measure: 1385.8 ± 0.6 px² (std = 2.9)

2D area (with soft clipping)

Area of 100 disks ($r = 21$ px) with sub-pixel shifts

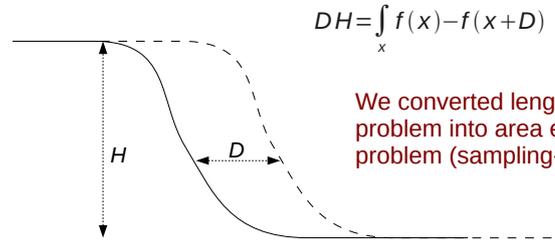


Expected measure: 1385.442360 px²
 Grey-value measure: 1385.370 ± 0.003 px² (std = 0.013)
 Binary measure: 1385.31 ± 0.08 px² (std = 0.39)

(For soft clipping I increased the sampling density 4 times)

2D perimeter

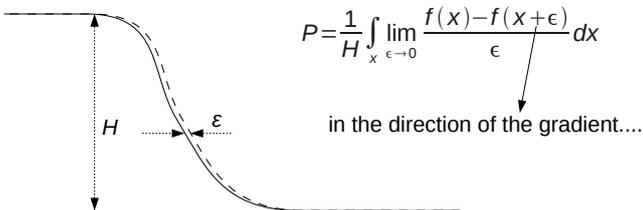
- Given a grey-value object with a constant intensity H
- If we extend the object by a fixed distance D , the volume of the extension is given by: $P D H$ ($P =$ perimeter)



We converted length estimation problem into area estimation problem (sampling-invariant!)

2D perimeter

- Given a grey-value object with a constant intensity H
- If we extend the object by a fixed distance ϵ , the area of the extension is given by: $P \epsilon H$ ($P =$ perimeter)



2D perimeter

- Soft clipping
- Gradient magnitude $\sqrt{(\frac{\partial f}{\partial x})^2 + (\frac{\partial f}{\partial y})^2}$
- Integration (sum)

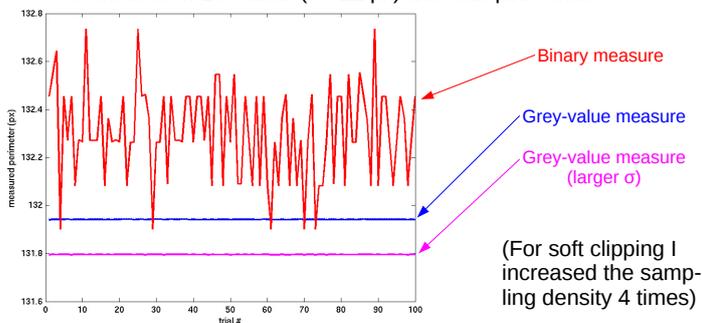


We're using Gaussian gradients!

$$\frac{\partial}{\partial x} (f \otimes G) = f \otimes \frac{\partial}{\partial x} G$$

2D perimeter

Perimeter of 100 disks ($r = 21$ px) with sub-pixel shifts

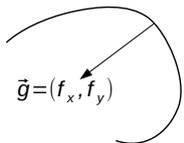


Expected measure: 131.946891 px
 Grey-value measure: 131.9415 ± 0.0001 px (std = 0.0006)
 with larger σ : 131.7958 ± 0.0001 px (std = 0.0006)
 Binary measure: 132.04 ± 0.01 px (std = 0.07)

(For soft clipping I increased the sampling density 4 times)

Isophote curvature

- Contour direction: $\vec{c} = (-f_y, f_x)$
 $\theta = \arccos\left(\frac{-f_y}{|g|}\right) = \arcsin\left(\frac{f_x}{|g|}\right) = \arctan\left(\frac{-f_y}{f_x}\right)$
- To differentiate along the curve:
 $\frac{d}{ds} = \cos\theta \frac{\partial}{\partial x} + \sin\theta \frac{\partial}{\partial y} = \frac{-f_y}{|g|} \frac{\partial}{\partial x} + \frac{f_x}{|g|} \frac{\partial}{\partial y}$
- Curvature $\kappa =$ derivative of θ along the curve
 $\kappa = \frac{d\theta}{ds} = -\frac{f_{xx}f_y^2 - 2f_xf_yf_{xy} + f_{yy}f_x^2}{(f_x^2 + f_y^2)^{3/2}} = \frac{-f_{cc}}{|g|}$
- 3D version more involved: eigenvalues of Hessian...



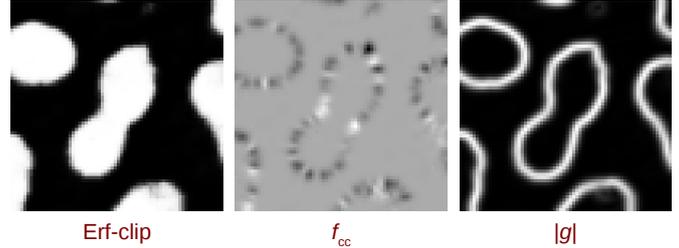
Bending energy

- Often used as a shape descriptor
- Given by integral along the perimeter of the square of curvature
- Integrate along perimeter by multiplying by $|g|$ and integrating over the image

$$B.E. = \int_{\text{contour}} \kappa^2 ds = \iint_{\text{image}} \kappa^2 |g| dx dy = \iint_{\text{image}} \frac{f_{cc}^2}{|g|} dx dy$$

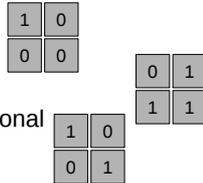
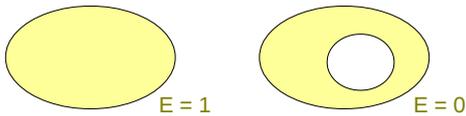
Bending energy

- Often used as a shape descriptor
- Given by integral along the perimeter of the square of curvature
- Integrate along perimeter by multiplying by $|g|$ and integrating over the image



Euler number

- Euler number
 - In 2D: # of objects - # of holes
 - In 3D: # of objects - # of tunnels + # of cavities
- Gray's algorithm
 - Computes Euler number based on 2x2 image regions
 - $E = (C_1 - C_2 - 2C_3) / 4$
 - C_1 = # of 2x2 regions with only 1 pixel set
 - C_2 = # of 2x2 regions with 3 pixels set
 - C_3 = # of 2x2 regions 2 pixels set in a diagonal

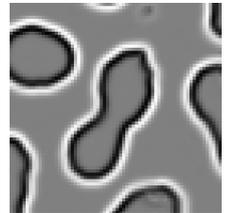


Euler number

- Integral of curvature along a closed contour is always 2π , a hole in an object contributes with -2π
- Integral of second derivative in gradient direction also yields a constant 2π for a closed contour

$$\text{Euler number} = \frac{1}{2\pi} \int_{\text{contour}} \kappa ds = \frac{1}{2\pi} \iint_{\text{image}} \kappa |g| dx dy = \frac{1}{2\pi} \iint_{\text{image}} -f_{cc} dx dy$$

$$\text{Euler number} = \frac{1}{2\pi} \iint_{\text{image}} f_{gg} dx dy$$



Summary

- It is important to use unbiased measures
- Filtering can introduce bias
- Area/volume = integral over image
- Perimeter/surface area
 - obtained by converting to area measurement problem
- Curvature
 - computed through 2nd derivative along countour
 - bending energy & Euler number
- Prepare image by soft clipping
 - (equivalent to thresholding, but without loss of band limitation)