

The Coverage model
Nataša Sladoje and Joakim Lindblad

Introduction to the workshop
Introduction to the topic
The Coverage Model

Image analysis with subpixel precision - The Coverage model

Nataša Sladoje and Joakim Lindblad
sladoje@uns.ac.rs, joakim@cb.uu.se

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Models and methods for precise image analysis

Few words about the project:

- Info**
 - <http://imft.ftn.uns.ac.rs/~natasja/CoverageModelCourse>
 - Joakim and Nataša are sitting in Room 2144
- Goals**
 - To initiate concrete research tracks which include practical application of the framework of the coverage model to already existing research projects at CBA.
 - To further develop the framework through cooperation.
 - Collaborations initiated will be intensively carried on during the visit, along with the course, which will serve as a discussion platform/idea incubator. The collaborating projects will be continued, with an aim to be brought to some results and conclusions (hopefully, some publications) during the expected additional visit the following year.

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Models and methods for precise image analysis

- Content**
 - Workshop (course) for initial exchange of ideas and experiences related to the topic, according to the schedule available from the course page (Sept 11–25)
 - Further work on project tasks for students interested in applying, or further developing, the described methods (Sept 25 – Oct 5);
 - Presentation (defence) of the project results. If supported by a moderately sized report, this work is assigned 3 ECTS credits (Oct 5)
 - Even further collaborative work on promising projects (Oct 5 – (Oct 25) ...).

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Coverage model - what and why, briefly

- A particular way to represent shapes/objects in images - **Coverage representation** - will be presented.
- Main motivation to introduce it is to enable **increased precision** of image processing tasks, compared to the classical - crisp/binary - shape representation.
- Ways how to obtain coverage representation - **coverage segmentation algorithms** - will be presented.
- Performance of the model, esp. in terms of **feature extraction**, will be explored with intention to motivate its usage.
- Examples of **applications** of the model will be given.

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Motivation and context

- The task of **Image Analysis** is to **extract relevant information from images**.
- Numerical descriptors**, such as area, perimeter, and moments of objects are often of interest, for the tasks of shape analysis, classification, etc.

The standard image analysis task (and its solution)

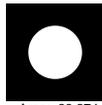
- Sample preparation and Imaging
- Pre-processing (optional)
- Segmentation
 - Usually crisp
- Feature extraction
 - Discrete representation problematic
- Classification

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Motivation - feature estimation

Crisp discrete object representations, especially at low spatial resolutions, put strong limitations to the precision of estimated features:



Area: 28.274
Perim: 18.850



Area: 31.000
Perim: 19.422



Area: 26.000
Perim: 17.526



Area: 28.000
Perim: 18.867



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Motivation - feature extraction

Unrealistically low resolution?

- Low resolution will always be a challenge; the more powerful imaging devices, the smaller objects are of interest!
- Partial Volume Effect in high resolution 3D images; consistent small displacement of object boundaries leads to significant errors of feature estimates.

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Approach based on fuzzy sets

A fuzzy set of a reference set is a set of ordered pairs

$$F = \{ \langle x, \mu_F(x) \rangle \mid x \in X \},$$

where the membership function $\mu_F : X \rightarrow [0, 1]$ indicates, for each element $x \in X$, to what extent it belongs to the fuzzy set F .

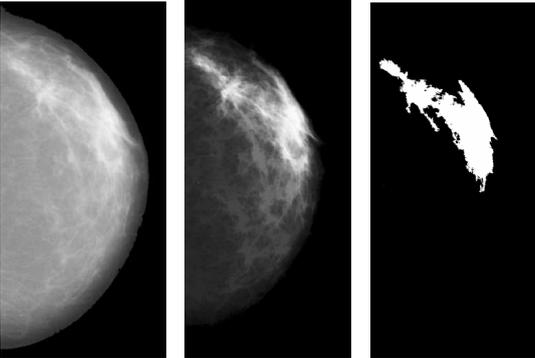
Observations:

- A fuzzy set is defined/identified by its membership function
- A crisp set is a special case of fuzzy set, where membership function takes only two values, 0 and 1.

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An example of a fuzzy segmented image

Breast density, as measured from the **volume of dense tissue** in the breast is considered to indicate a risk factor for breast cancer.



A digitized X-ray mammogram, the fuzzy connectivity scene of a dense (fibroglandular) region (as opposed to fatty regions), and a corresponding crisp region.

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The Fuzzy Approach

- **Do not throw away information by making crisp decisions.**
- The more nuanced view of a fuzzy approach allows **preservation of more information.**
- A representation based on **fuzzy sets** can provide numerical descriptors with **higher precision** than what can be achieved from a crisp representation.

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The Fuzzy Approach

A standard image analysis task and its fuzzy solution

- 1 Sample preparation and Imaging
- 2 Pre-processing (optional)
- 3 **Segmentation**
 - Fuzzy segmentation (a lot of **freedom**)
- 4 **Feature extraction**
 - Fuzzy representation provides robustness and precision
 - May be **difficult to interpret** the results; different meanings of memberships
- 5 **Classification, statistical evaluation, ...**

New entries in the "standard chain of tasks" required:

- New segmentation methods that result in fuzzy representations;
- New analysis methods that can be applied to fuzzy object representations;
- New ways of interpreting and understanding the obtained results.

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The Fuzzy Approach

Important observations

- The original grey levels are, in general, **not directly used** as fuzzy representations.
- Appropriately designed fuzzy segmentation methods combine original grey levels together with several other types of information to define membership value of a pixel to an object.
- Meaning of grey levels in a fuzzy segmented image is always a consequence of many criteria, many of them only implicitly present.
- Instead of dependence on the properties of imaging devices, we are dependent on criteria used for fuzzy segmentation.
- Interpretation of results can become rather difficult.

The Coverage Model

- Keep good sides of fuzzy; stay close to the digital image, high information content, soft boundaries, robustness.
- Restrict to **one single meaning of memberships**; clear unique interpretation, enabling stronger theoretical results.

The Coverage Model

- Let the (membership) value of an image element be equal to its relative coverage by the image object.
- A representation close to the original (discrete) image data.
- Based on very weak assumptions about the imaged objects.
- Utilizing the coverage information, significant improvement in precision of extracted feature values can be reached.

Pixel coverage digitization

Let a square grid in 2D be given. The Voronoi region associated to a grid point $(i, j) \in \mathbb{Z}^2$ is called pixel $p_{(i,j)}$.

Definition (non-quantized case)

For a given continuous object $S \subset \mathbb{R}^2$, inscribed into an integer grid with pixels $p_{(i,j)}$, the *pixel coverage digitization* of S is

$$\mathcal{D}(S) = \left\{ \left((i, j), \frac{A(p_{(i,j)} \cap S)}{A(p_{(i,j)})} \right) \mid (i, j) \in \mathbb{Z}^2 \right\},$$

where $A(X)$ denotes the area of a set X .

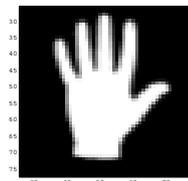
Digital images \rightarrow Quantized grey values

Definition (n -level quantized case)

$$\mathcal{D}^n(S) = \left\{ \left((i, j), \frac{1}{n} \left\lfloor n \frac{A(p_{(i,j)} \cap S)}{A(p_{(i,j)})} + \frac{1}{2} \right\rfloor \right) \mid (i, j) \in \mathbb{Z}^2 \right\},$$

where $\lfloor x \rfloor$ denotes the largest integer not greater than x .

Properties of coverage representations

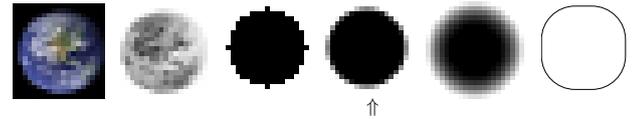


Intuitively, a coverage representation of a crisp object, with a well defined continuous border, is characterized by the presence of **homogeneous connected regions of "pure" pixels**, completely covered by either object or background **separated by thin layers of "mixed" pixels**, i.e., those partially covered by both object and background.

If a crisp continuous set has a reasonably smooth boundary and is represented at a high enough resolution, then **the fuzzy border** of its digital coverage representation **is not more than one pixel thick**.

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Lots of possible representations...

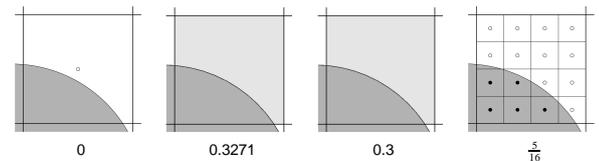


So, what do we want, and what do we not want?

- First and second representations preserve quite some information, but are too dependent on imaging;
- Binary representation sacrifices too much information;
- We cannot complain on the forth one!
- Too flexible definition of membership values in a (general) fuzzy representation leads to difficult interpretations;
- Continuous models often impose too strong (and unrealistic) assumptions on the image objects.

Pixel coverage digitization

The membership value of a pixel is equal to its relative coverage by an imaged object (here a part of a disk).



- Gauss digitization assigns value 0 to the observed pixel.
- By coverage digitization assigned value is 0.3271.
- If 10-level quantized coverage digitization is used, assigned value is 0.3.
- If coverage is approximated by 4-sampled coverage digitization, assigned value is $\frac{5}{16}$.

The Coverage Model

The image analysis task and its coverage solution

- 1 Sample preparation and Imaging
- 2 Pre-processing (optional)
- 3 **Segmentation**
 - Coverage segmentation (restricted freedom)
- 4 **Feature extraction**
 - Estimate features from the coverage representation
 - Easy to interpret the results, robustness and precision
- 5 Classification, statistical evaluation, ...

New entries in the "standard chain of tasks" required:

- New segmentation methods that result in coverage representations;
- New analysis methods that can be applied to coverage object representations.

However, there is no need for new ways of interpreting and understanding the obtained results.

Feature extraction revisited



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Area: 28.274
Perim: 18.428



Area: 28.274
Perim: 18.684



Area: 28.274
Perim: 18.675



Area: 28.274
Perim: 18.712



Area: 28.274
Perim: 18.654



Area: 28.274
Perim: 18.692